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5.3.2 Design Member Moment Capacity

Designers must ensure that the design bending moment (M^*) $\leq \phi M_b$ for all beam segments. The tabulated values of design member moment capacity (ϕM_b) are determined in accordance with Clause 5.6.1.4 of AS 4100 as:

$$\phi M_{\rm b} = \phi \alpha_{\rm m} \alpha_{\rm s} M_{\rm s} \leq \phi M_{\rm s}$$

where $\phi = 0.9$ (Table 3.4 of AS 4100)

 $\alpha_{\rm m}$ = moment modification factor (Clause 5.6.1.1 of AS 4100)

= 1.0 (Assumed for all entries in Tables 5.3-1 to 5.3-2 – based on uniform moment case)

 α_s = slenderness reduction modification factor (Clause 5.6.1.1 of AS 4100)

= 0.6
$$\left\{ \sqrt{\left[\left(\frac{M_s}{M_{oa}} \right)^2 + 3 \right]} - \left(\frac{M_s}{M_{oa}} \right) \right\}$$
 (Equation 5.6.1.1(2) of AS 4100)

 $M_{\text{oa}} = M_{\text{o}}$ – the reference buckling moment (Clause 5.6.1.1(a)(iv)(A) of AS 4100)

$$= \sqrt{\frac{\pi^2 E I_y}{L_e^2} GJ}$$
 (equation 5.6.1.1(3) of AS 4100 with $I_w = 0$)

 $L_{\rm e}$ = effective length of beam segment.

5.3.3 Beam Effective Length

The value of $\phi M_{\rm b}$ depends on the effective length ($L_{\rm e}$) of the flexural member. $L_{\rm e}$ is determined by:

 $L_{\rm e} = k_{\rm t} \, k_{\rm l} \, k_{\rm r} \, L$ (Clause 5.6.3 of AS 4100) where $k_{\rm t} = {\rm twist} \, {\rm restraint} \, {\rm factor}$ (Table 5.6.3(1) of AS 4100) $k_{\rm l} = {\rm load} \, {\rm height} \, {\rm factor}$ (Table 5.6.3(2) of AS 4100) $k_{\rm r} = {\rm lateral} \, {\rm rotation} \, {\rm restraint} \, {\rm factor}$ (Table 5.6.3(3) of AS 4100) $L = {\rm length} \, {\rm of} \, {\rm segment}$

Ref. [5.4] provides guidance on the restraint conditions on flexural members provided by many common structural steelwork connections. Additionally, Ref. [5.5] considers further guidance on unbraced cantilevers.

5.3.4 Other Loading and Restraint Conditions

The design member moment capacities presented in the 5.3 series tables can be used for other loading conditions. For these situations the effective length ($L_{\rm e}$) corresponding to the actual length and restraint conditions must be assessed and the appropriate value of $\alpha_{\rm m}$ determined in accordance with Clause 5.6.1.1(a) of AS 4100. The design member moment capacity can then be determined as the *lesser* of:

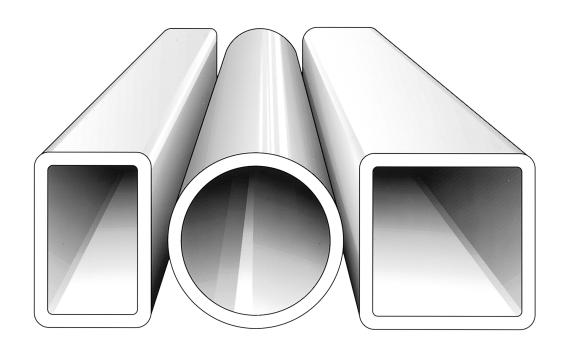
$$\begin{array}{rcl} & \phi M_{\rm SX} &=& \phi Z_{\rm ex} \, f_{\rm y} \\ & \text{and} & \phi M_{\rm b} &=& \phi \alpha_{\rm m} \, \alpha_{\rm s} \, Z_{\rm ex} \, f_{\rm y} \\ & \text{where} & \phi &=& 0.9 \text{ (Table 3.4 of AS 4100)} \\ & \phi M_{\rm b} &=& \alpha_{\rm m} \text{ times the value of } \phi M_{\rm b} \, (= \phi \alpha_{\rm s} \, Z_{\rm ex} \, f_{\rm y}) \text{ given in Tables 5.3-1 to 5.3-2.} \end{array}$$

Tables 5.3-1 to 5.3-2 are based on the most critical moment distribution – i.e. uniform moment over the entire beam segment ($\alpha_{\rm m}$ = 1.0). For other values of $\alpha_{\rm m}$, designers should use the *lesser* of $\phi M_{\rm sx}$ and $\alpha_{\rm m}$ ($\phi M_{\rm b}$) where $\phi M_{\rm b}$ is the value given in the appropriate table for the same effective length.



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